

AI Implication in Manufacturing

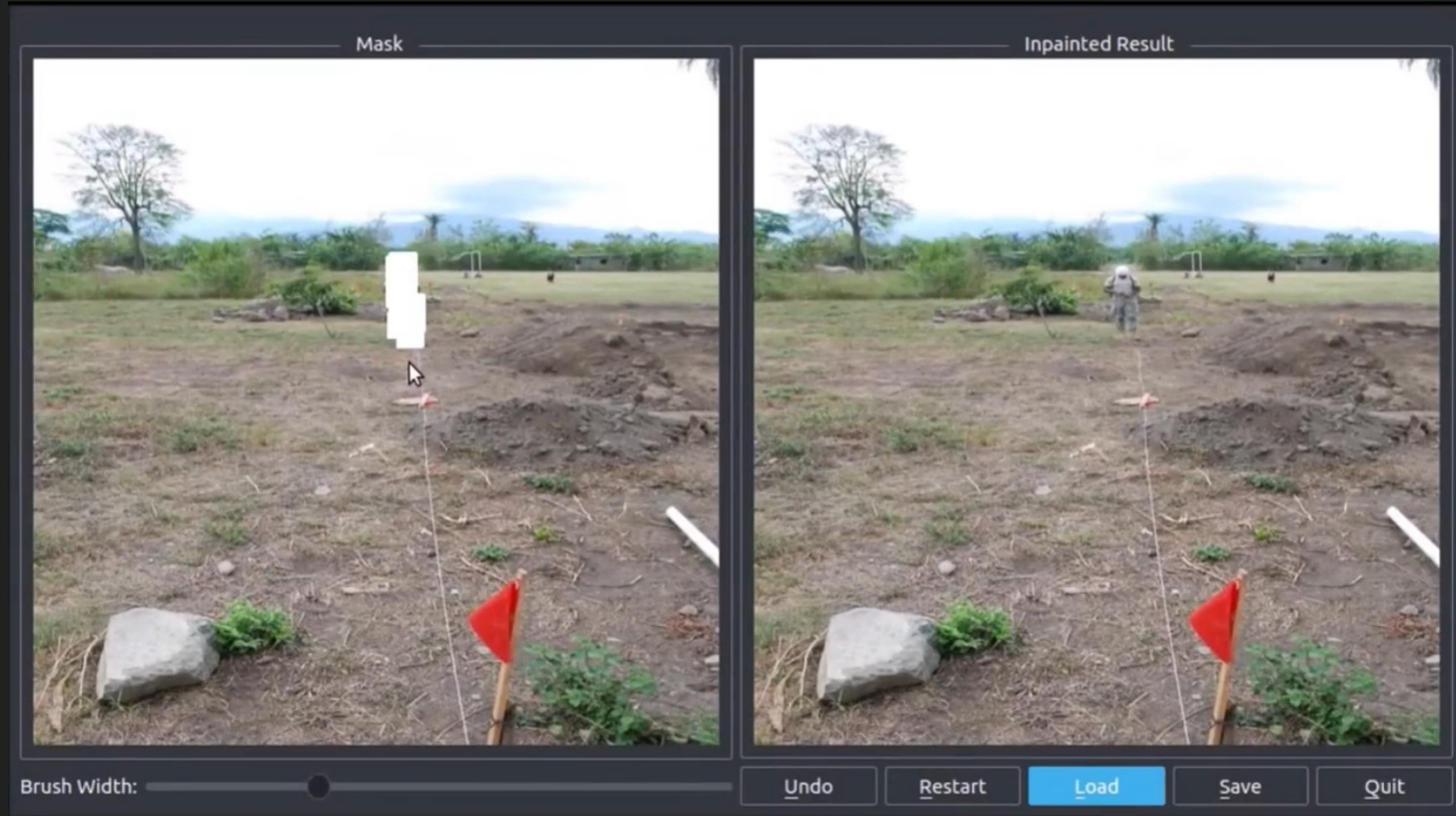
구성용



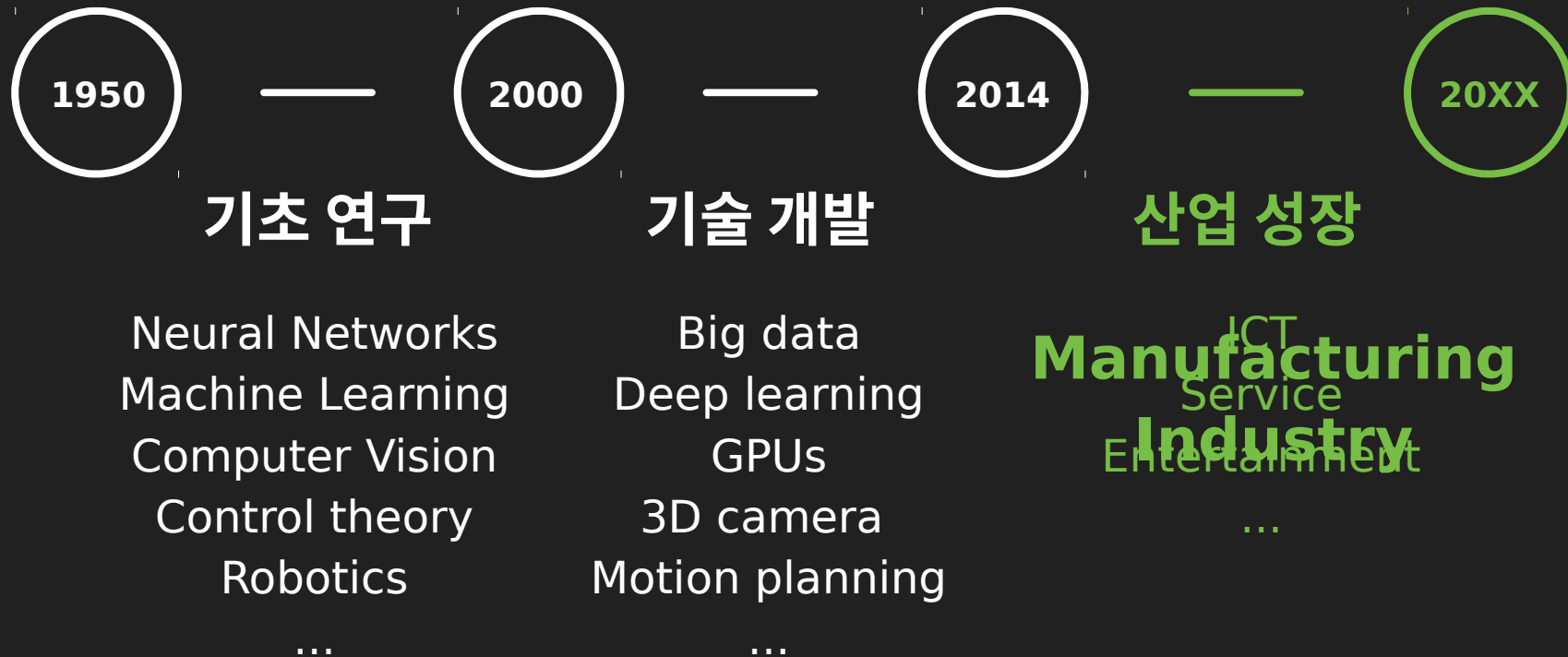
최근 나온 **로봇** 기술 보셨나요 ?



최근 나온 인공지능 기술 보셨나요 ?



인공지능 / 로봇 기술 발달



제조 산업 (Manufacturing Industry)

원재료를 인력이나 기계력 및 여러 다른 힘으로 **가공**하여 제품을 **대량 생산**하는 산업



제조 산업 (Manufacturing Industry)

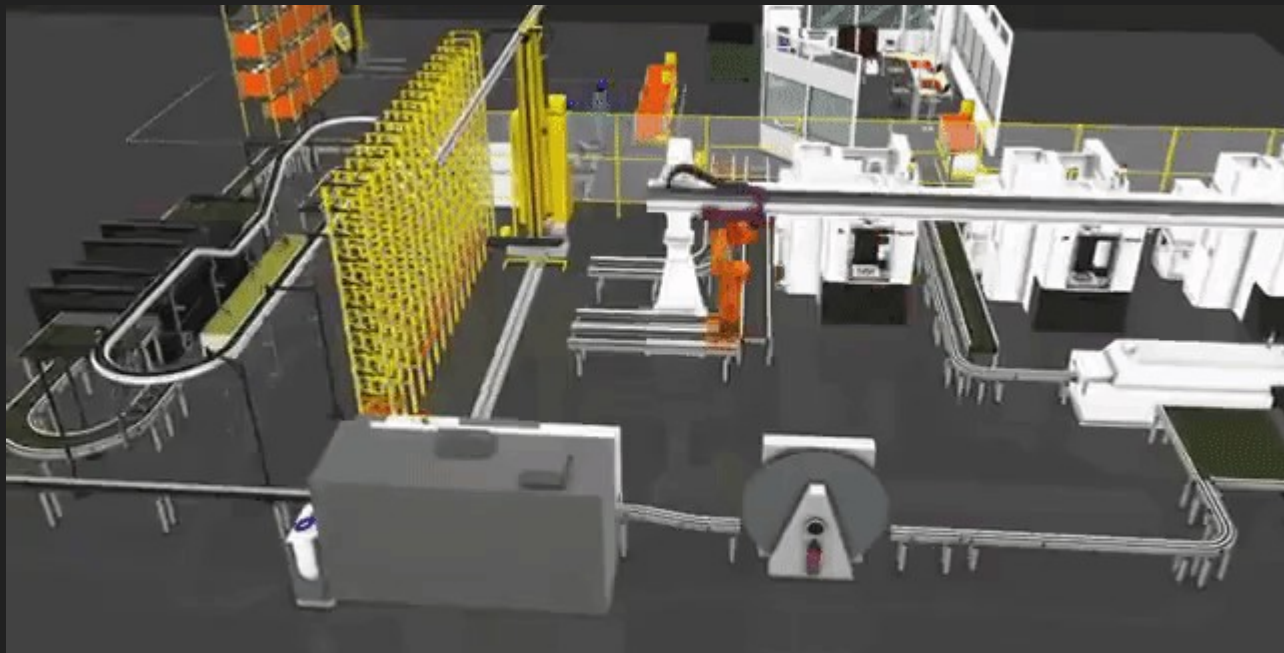
대량 생산

비싼 시설

긴 생산 라인

오래된 역사

Conservative!



오늘의 주제

새로운 기술

?



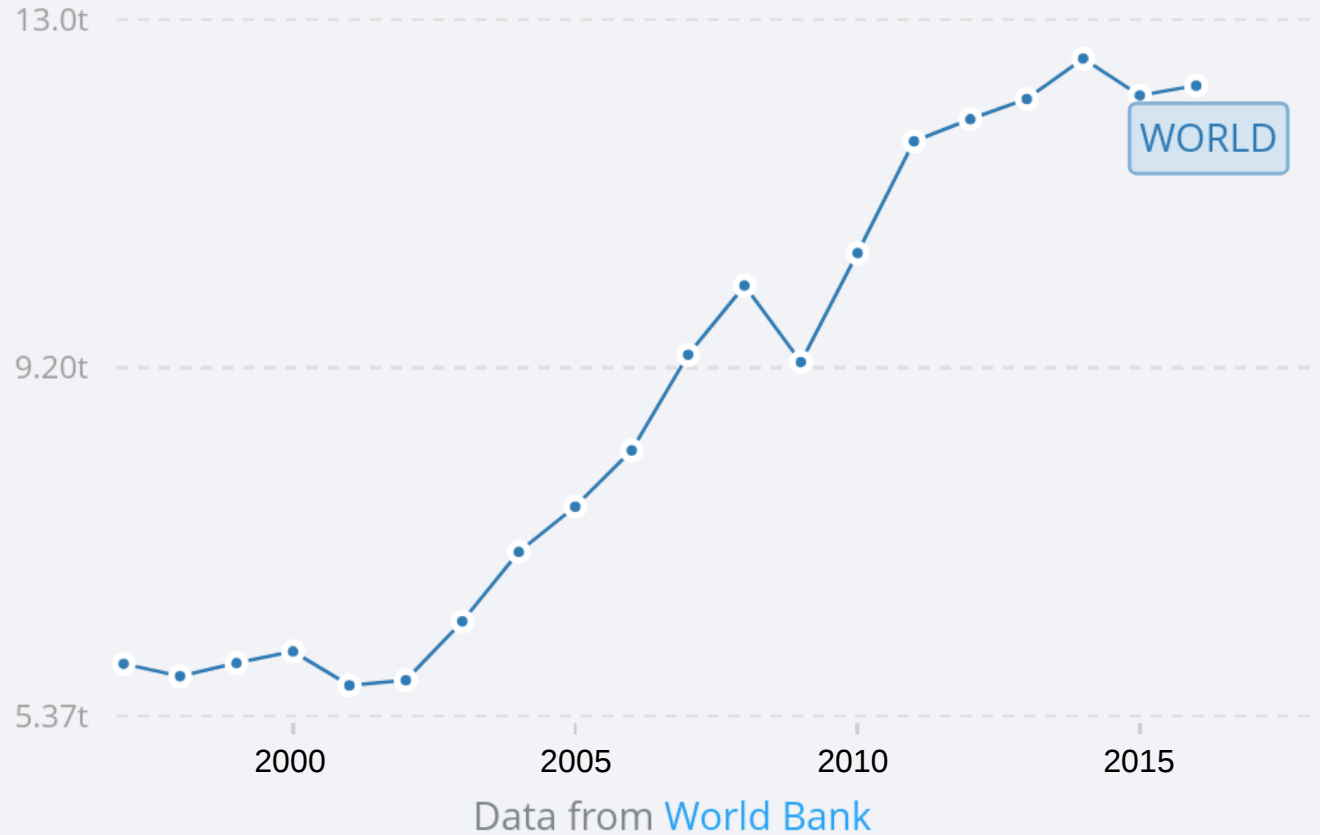
Conservative

산업의 변화

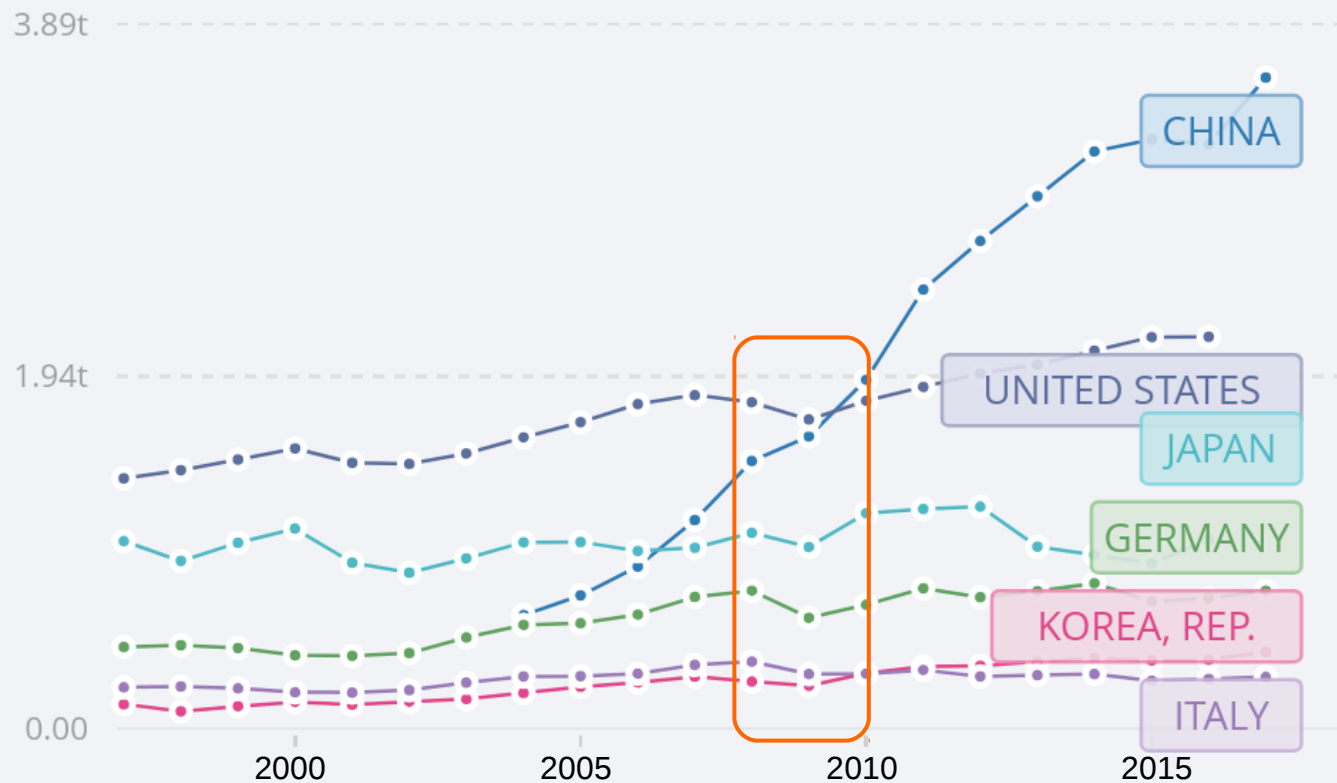
1. 산업 시장의 변화



Manufacturing, value added (current US\$)



Manufacturing, value added (current US\$)



Data from [World Bank](#)

노동 시장의 변화

노동 인구 감소, 인건비 상승

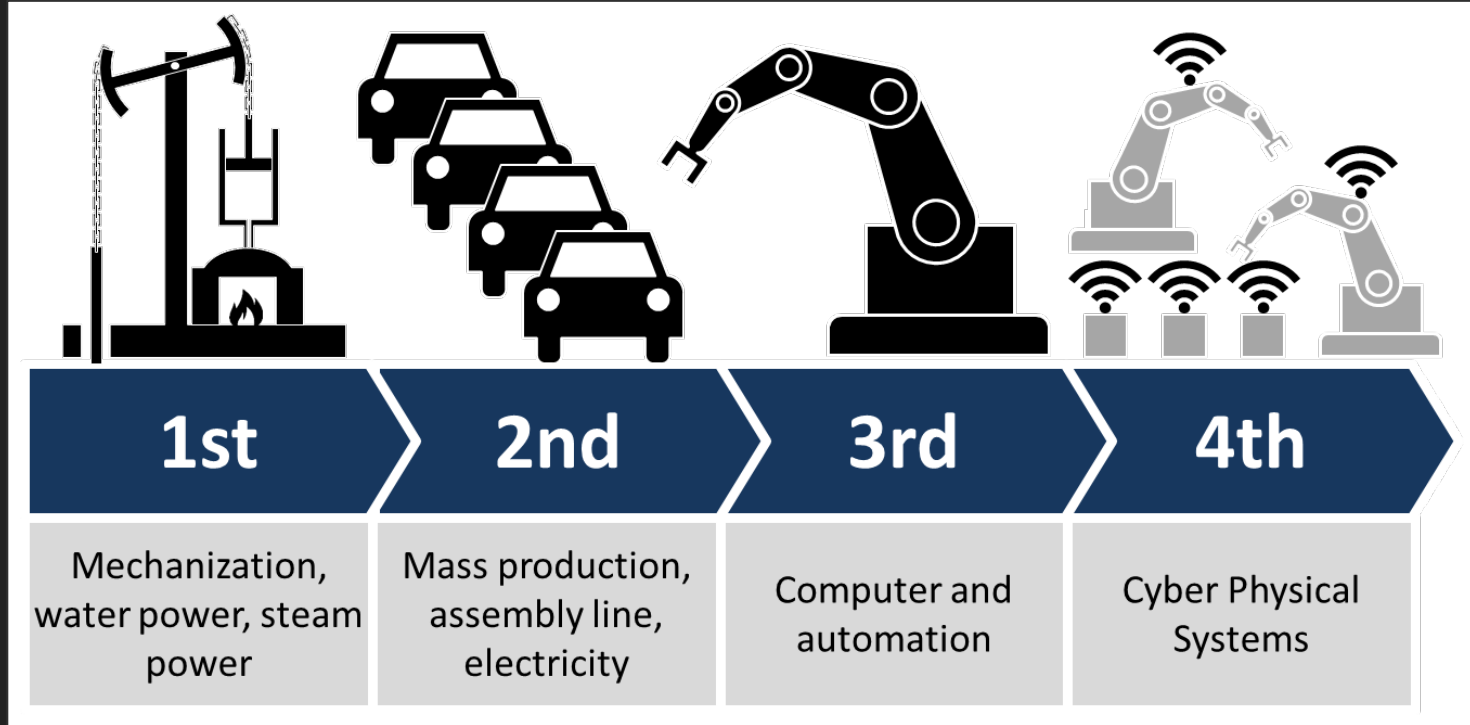
소비자 성향 변화

소품종 대량 생산 → 다품종 소량 생산



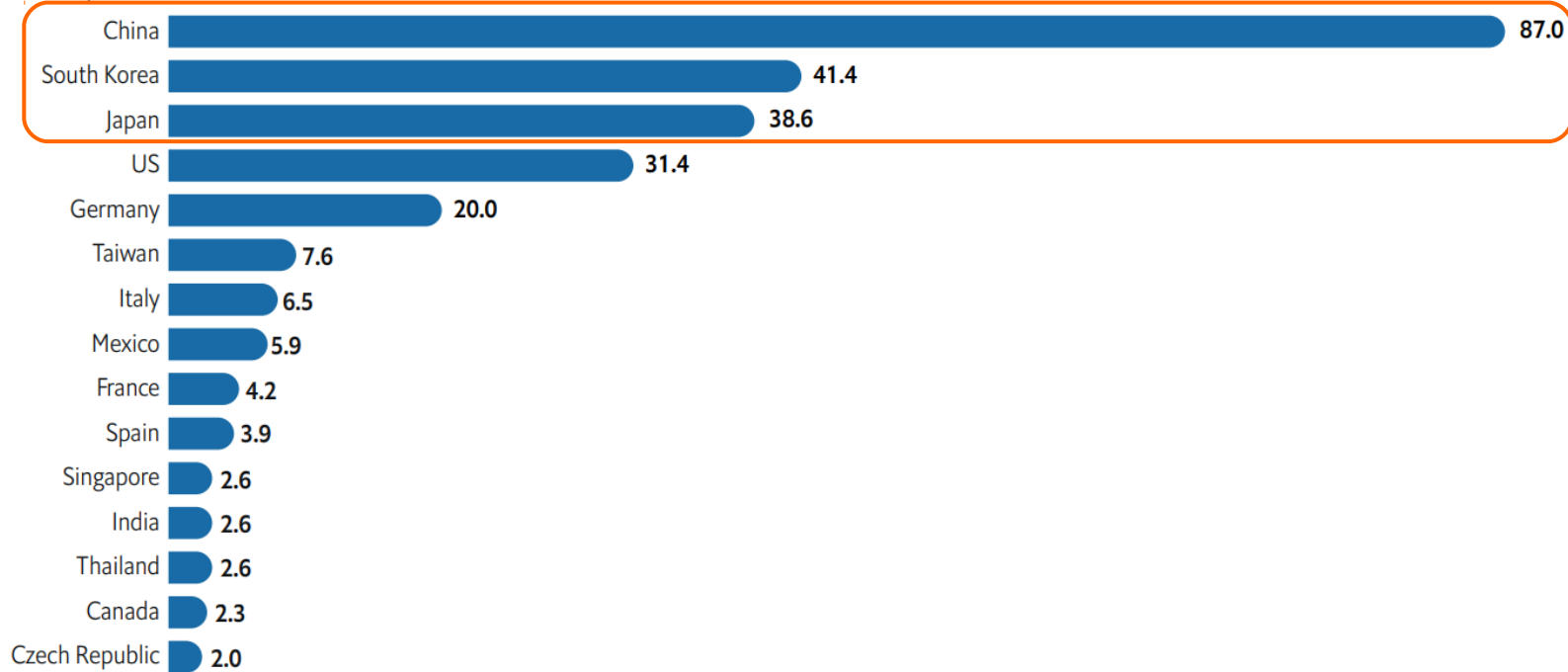
효율적이고 유연한 생산 시스템 도입 필요

Industry 4.0



Estimated worldwide annual supply of industrial robots, 10 largest markets, 2016

('000 units)



Source: International Federation of Robotics, *World Robotics 2017 Industrial Robots*.



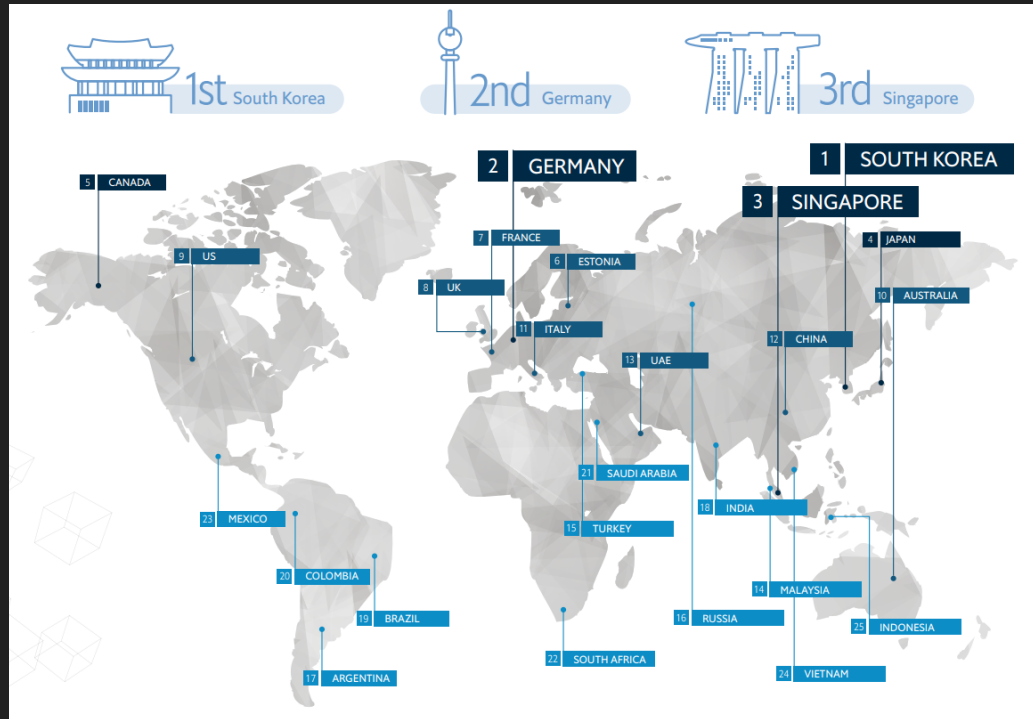
Automation Readiness Index 2018

How well-prepared 25 countries are for the challenges and opportunities of **intelligent automation**.

혁신 환경 평가
Innovation for automation

교육 정책 평가
Skills for an automated economy

노동 시장 정책 평가
Managing workplace transitions





2. 그랜드 챌린지

Pickit
ROBOT VISION MADE EASY





2004 – 2007 DARPA Grand Challenge

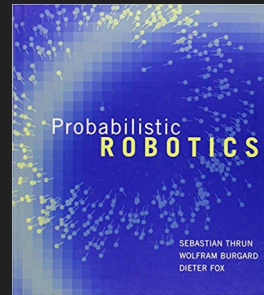
Sebastian Thrun 교수, Probabilistic Robotics 저자

2005 년 Stanford Racing Team 우승

2007 년 Sebastian Thrun 교수 구글에 합류

2012 년 구글 자율주행차 최초 시내 주행 성공

2017 년 Waymo 등 자율주행 자동차 스타트업



WAYMO

ImageNet Large Scale Visual Recognition Challenge

Fei Fei Li 교수

2010 년 부터 14M 이상 이미지 빅데이터 제공

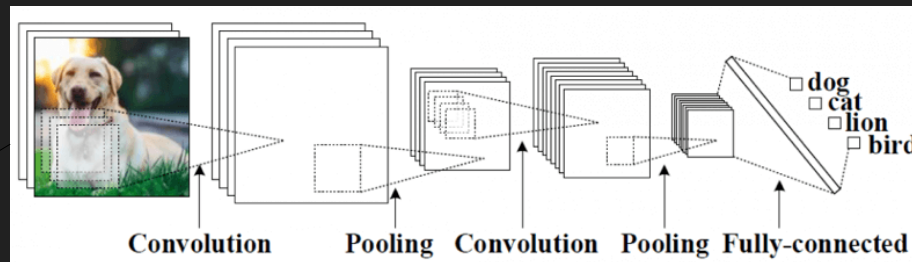
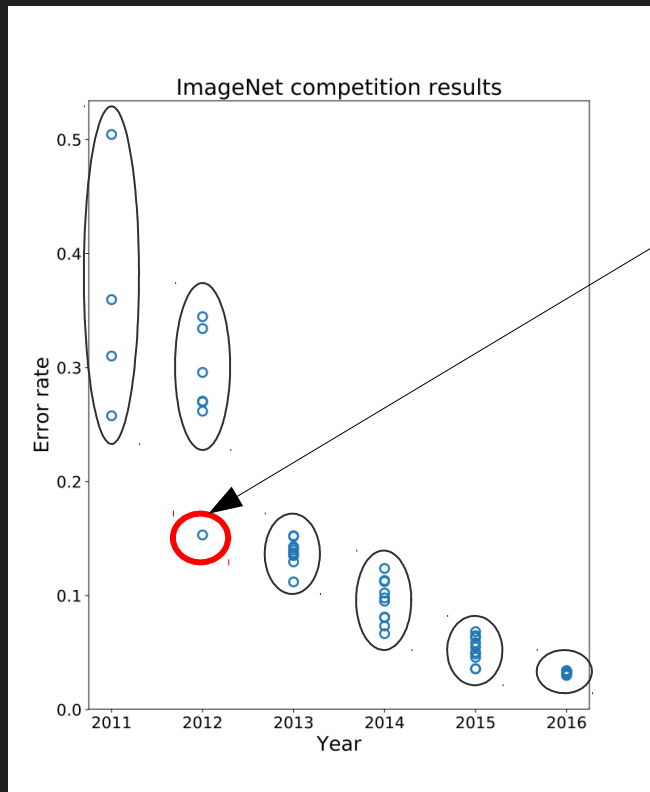
컴퓨터 비전 기술 챌린지 (이미지 인식 , 물체 검출 , 물체 인식 ...)



IMAGENET



ImageNet Large Scale Visual Recognition Challenge



Convolutional Neural Networks





100 STARTUPS USING ARTIFICIAL INTELLIGENCE TO TRANSFORM INDUSTRIES

CONVERSATIONAL AI/ BOTS



VISION



AUTO



ROBOTICS



CYBERSECURITY



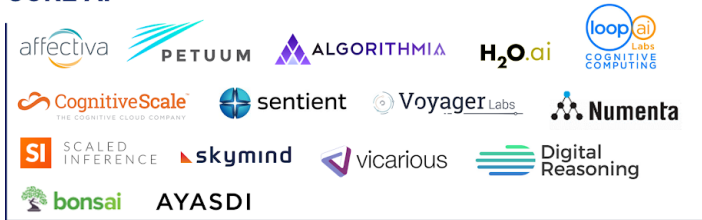
BUSINESS INTELLIGENCE & ANALYTICS



AD, SALES, CRM



CORE AI



HEALTHCARE



TEXT ANALYSIS/ GENERATION



IOT/IIOT



COMMERCE



FINTECH & INSURANCE



OTHER





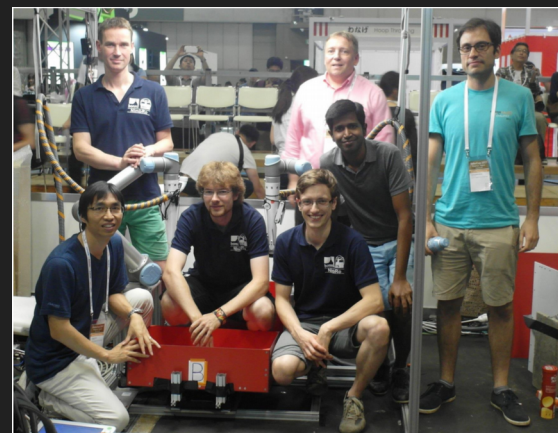
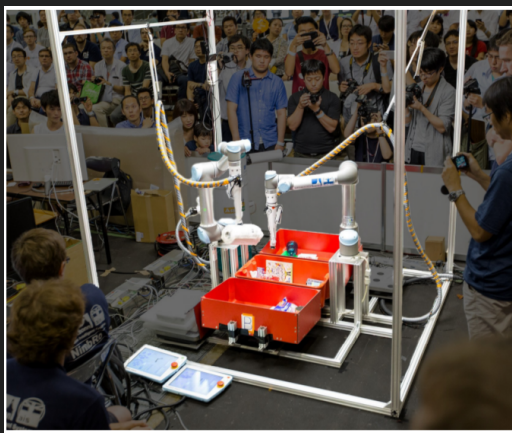
Amazon Warehouse



Amazon Robotics Challenge (2015 - 2017)

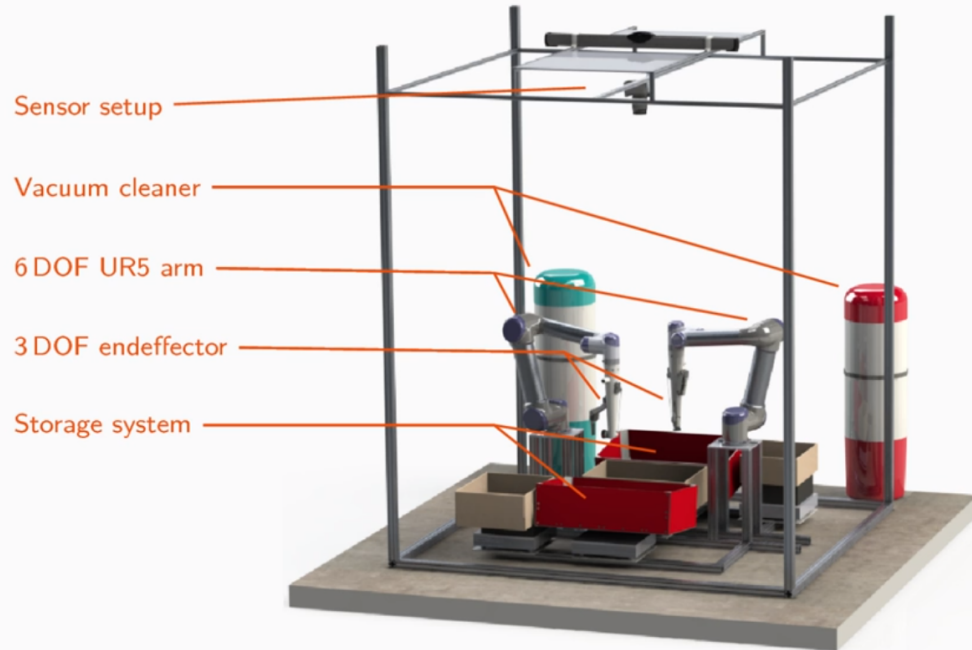
Stow task: Stowing of newly arrived items into a storage system

Pick task: Retrieval and packing of specific items from storage into boxes

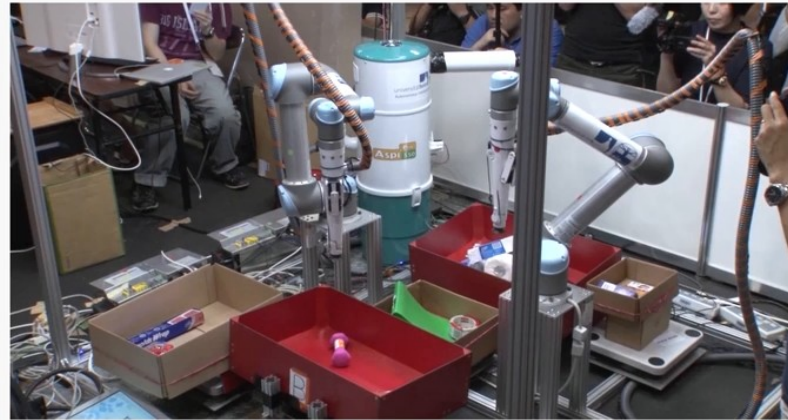
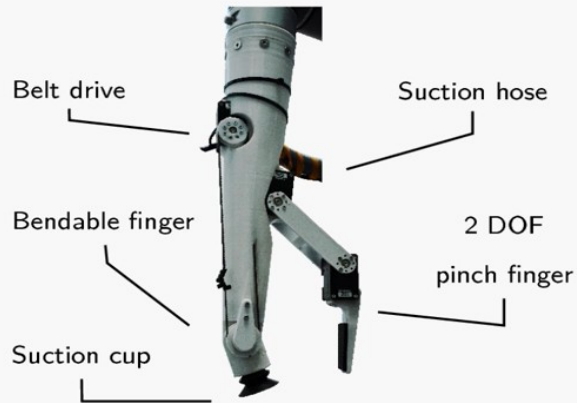


University of Bonn, Germany (Team NimbRo), 2nd place in 2016 and 2017

System Design



Endeffector Design



This endeffector design allows us to grasp items using suction...

Sensor Setup

Photoneo PhoXi®
3D-Scanner XL

Nikon D3400
photo camera

LED panels



[illegible]

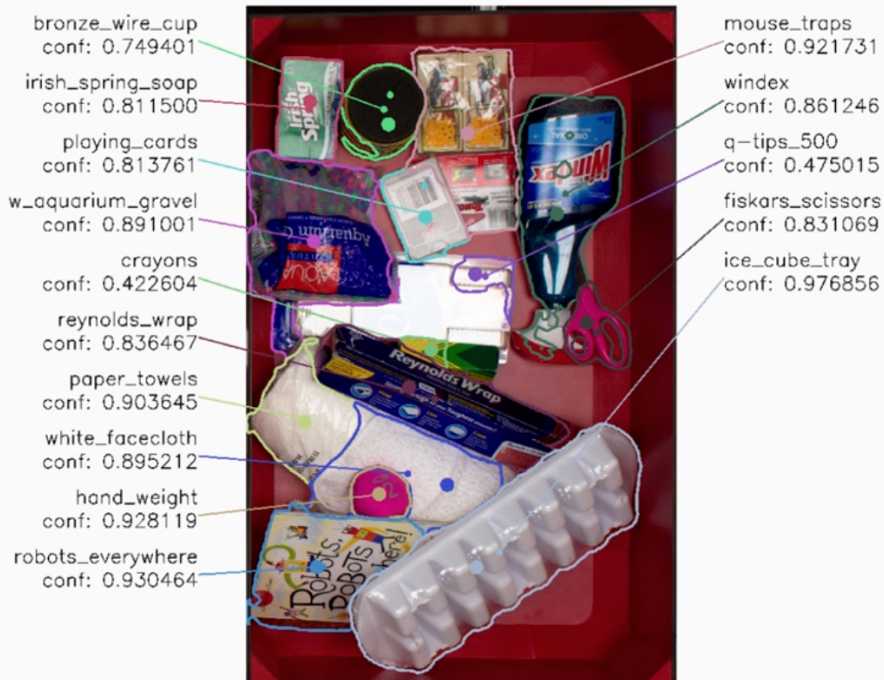
Guosheng Lin, Anton Milan, Chunhua Shen, Ian Reid
CVPR 2017

Data Capture, Scene Synthesis & Training



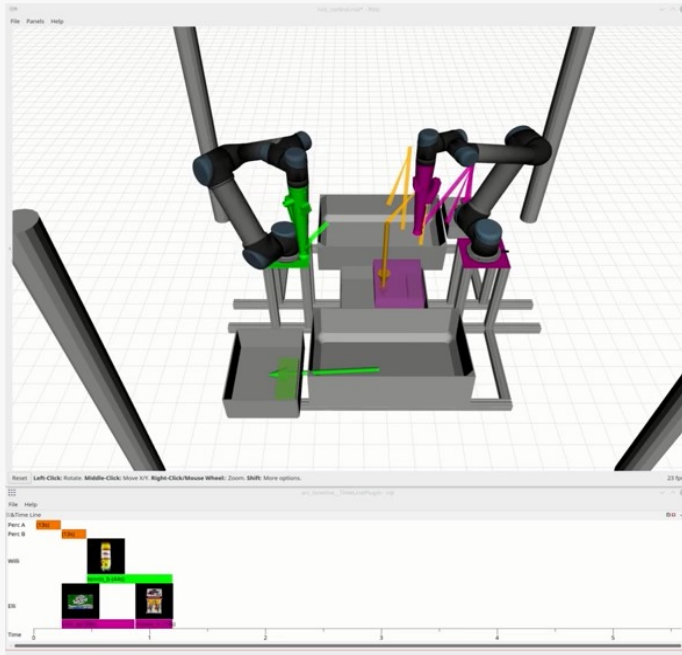
We capture new objects using a turntable and generate synthetic scenes on top of annotated dataset frames. Training is performed in ≈ 30 min on four Titan X cards.

Grasp Generation



- Object contours are extracted from segmentation.
- 2D grasp points with maximum distance to the contour are found.
- 6D grasp poses are calculated from depth and local surface normals.

Dual-Arm Coordination

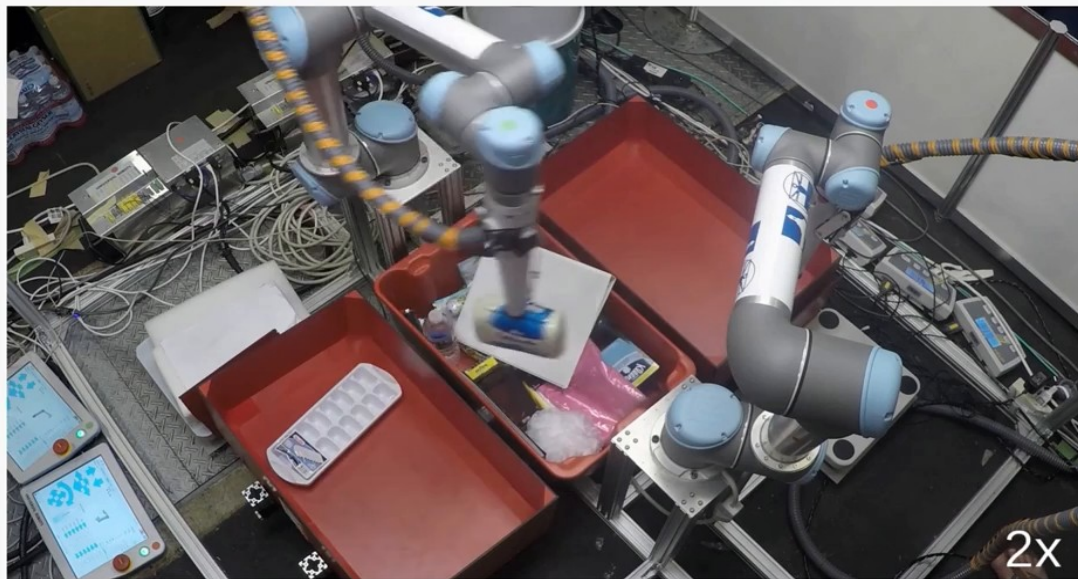


Collision free task assignment:

Green & purple: Arm activities.
Yellow: unassigned task generated from latest perception result.

Timeline of system activities.

Stow Task



Move all items from the tote into the storage system.

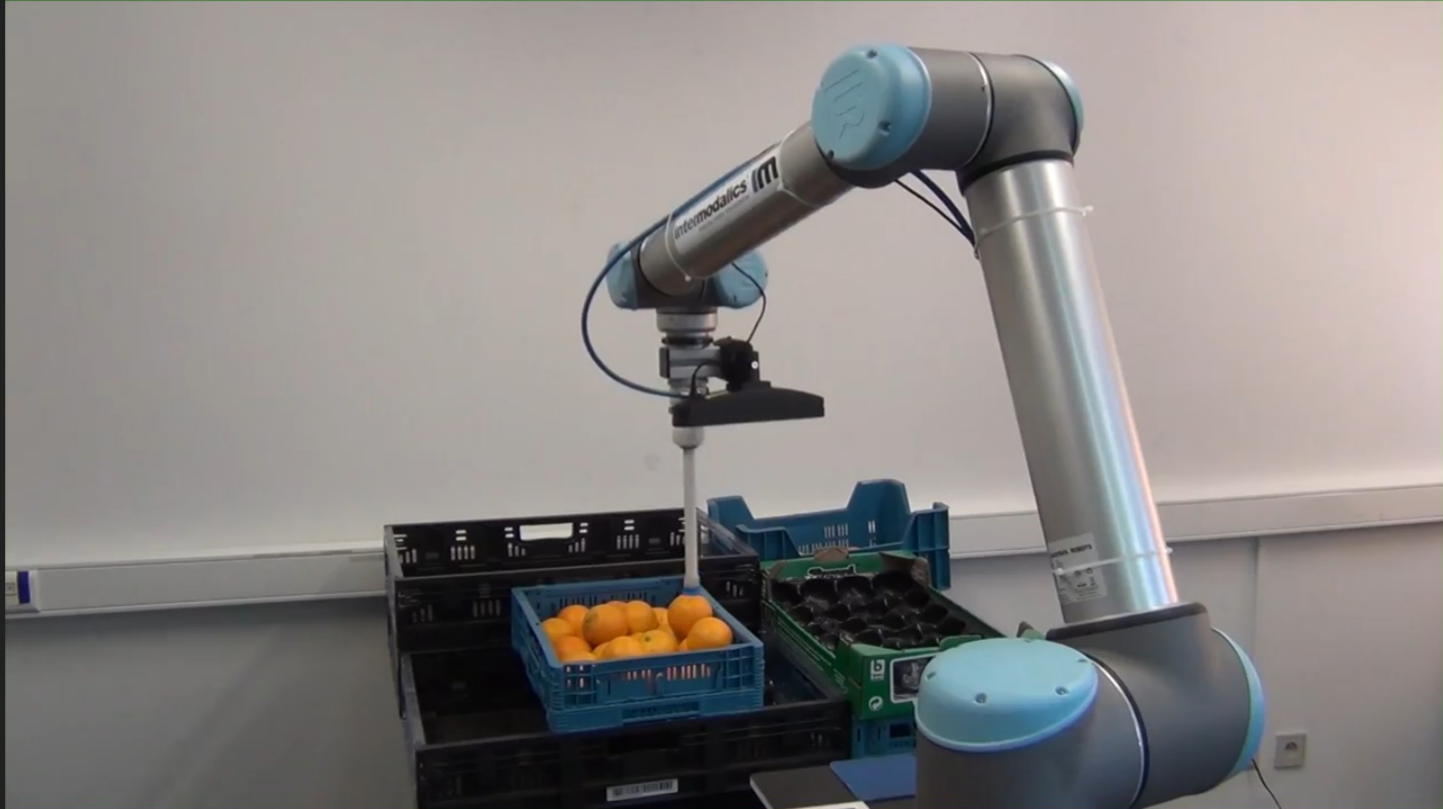
3. 핀테크 (Pin-tech) 스타트업



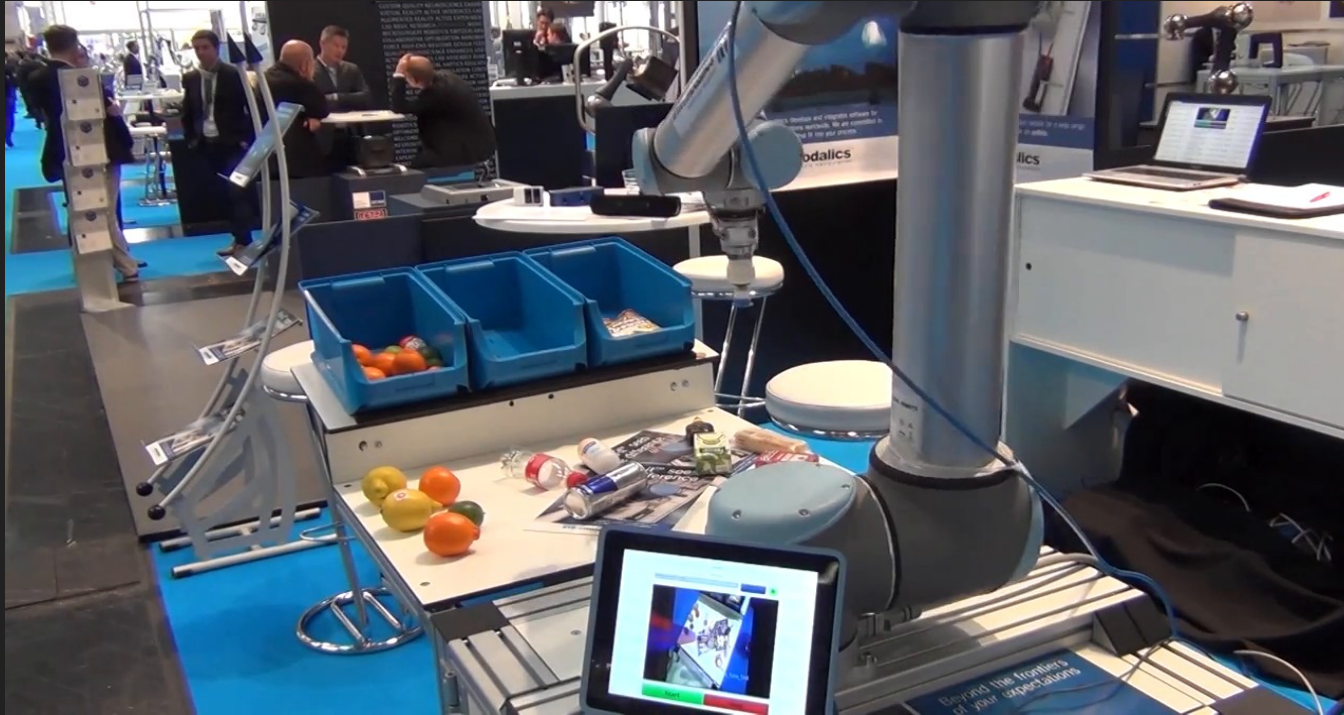
아마존 로보틱스 챌린지의 영향을 받은 스타트업



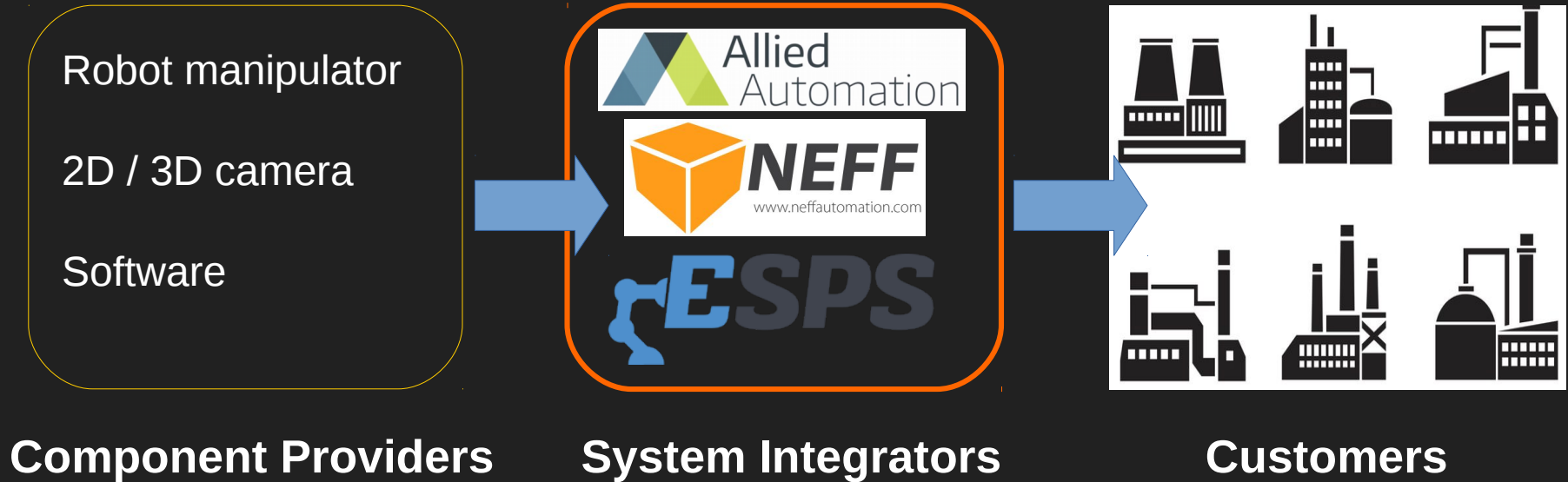
Pick-it 2014



Pick-it 2014 Automatica



Pick-it 2014 ~ 2016



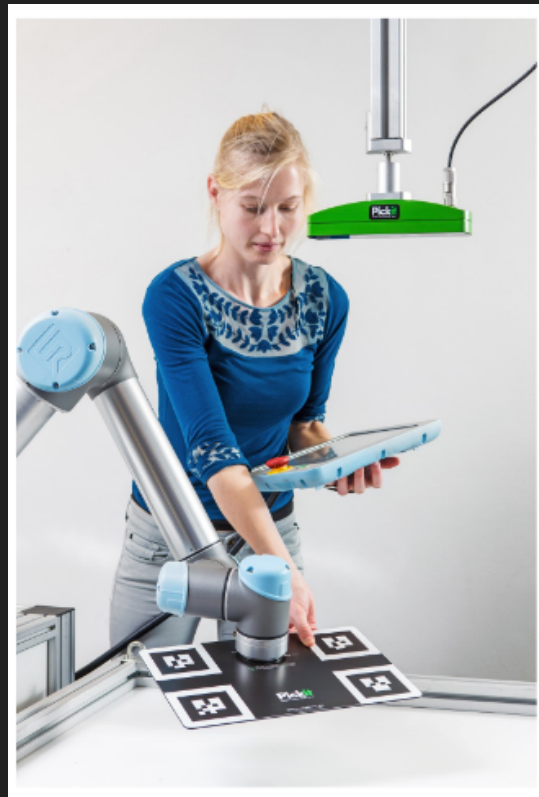
Pick-it 2014 ~ 2016

3D 비전 설치에
시간과 비용이 많이 들어요 .

Plug-and-Play

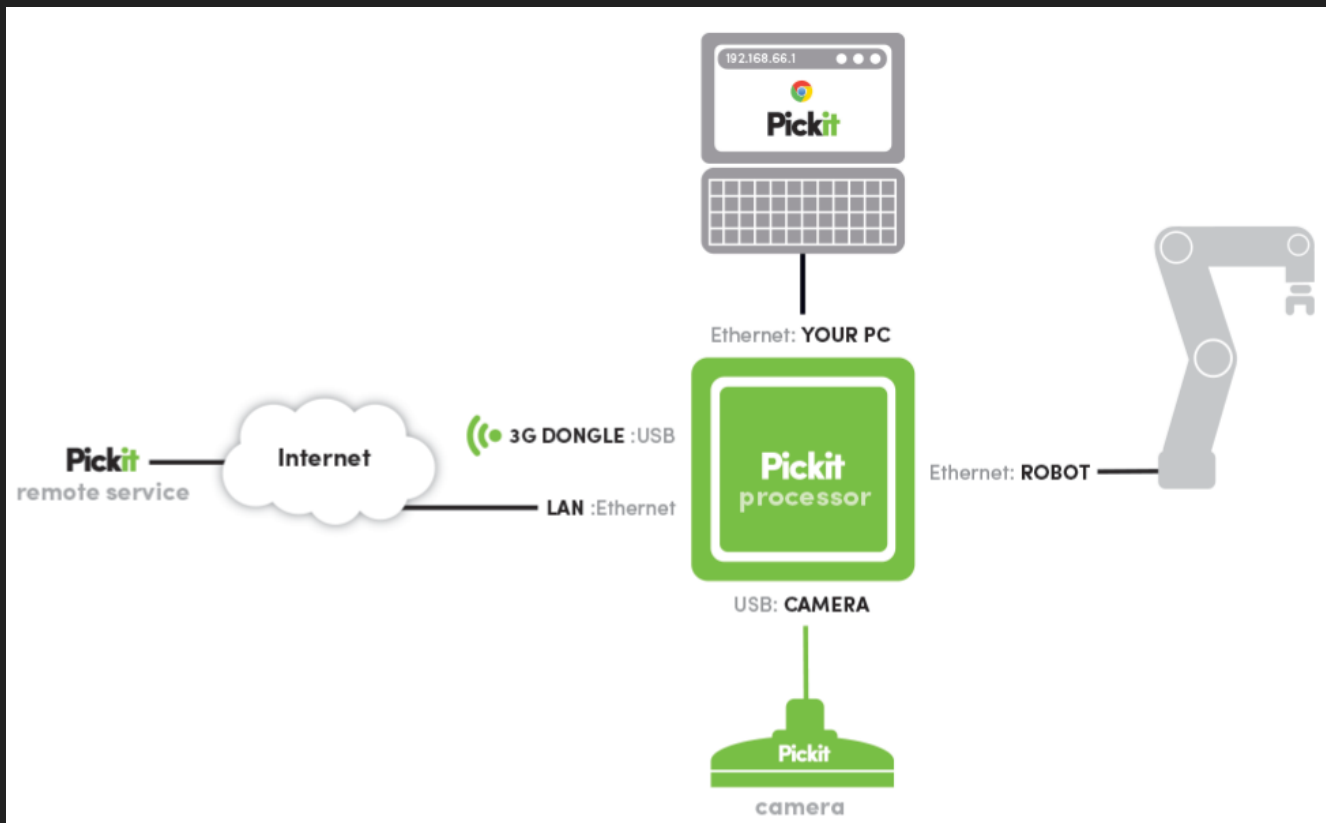
Easy-of-Use

First Pick on the First Day



Pick-it 2014 ~ 2016

서포트가
힘들어요 .



Pick-it 2014 ~ 2016

프로그래밍이
어려워요.

The screenshot displays the Pick-it 1.8.2 demo web interface. The main window shows a 3D view of a box containing several cylindrical objects, with yellow bounding boxes and green lines indicating detected features. The interface includes a top navigation bar with tabs for Configuration, Calibration, Region of Interest, Detection, Picking, and Files. The Detection tab is active, showing a 'Vision engine' section with options for Flex, Pattern, and Teach. Below this, there are sections for '1. Optimize 3D image', '2. Group points into clusters', '3. Reject clusters', '4. Fit objects to clusters', and '5. Filter objects'. The 'Objects table' at the bottom lists detected objects with their dimensions and scores.

#	Pickable	Valid	Dimensions mm	3D Scene Score min 0%	Points
1	✓	✓	Length 228 Diameter 70	██████████	2113
2	✓	✓	Length 52 Diameter 105	██████████	778
3	✓	✓	Length 54 Diameter 97	██████████	666
4	✓	✓	Length 55 Diameter 92	██████████	666
5	✓	✓	Length 194 Diameter 84	██████████	2338
6	✓	✓	Length 197 Diameter 88	██████████	2468
7	✓	✓	Length 71 Diameter 50	██████████	369
8	✗	✗	Length Diameter	██████████	10

Pick-it 2014 ~ 2016

프로그래밍이
어려워요 .



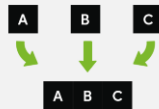
Machine loading
Automatic machine loading



Bin picking
Get parts out of the bin



Depalletizing
Get products on and of pallets



Kitting and assembly
Find parts for assembly



Pick and place
Pick from conveyors



UNIVERSAL ROBOTS

FANUC

ABB

YASKAWA

KUKA

STÄUBLI

Pick-it 2016



Pick-it 2017

Robot vision

WORKS FOR
DIFFERENT APPLICATIONS

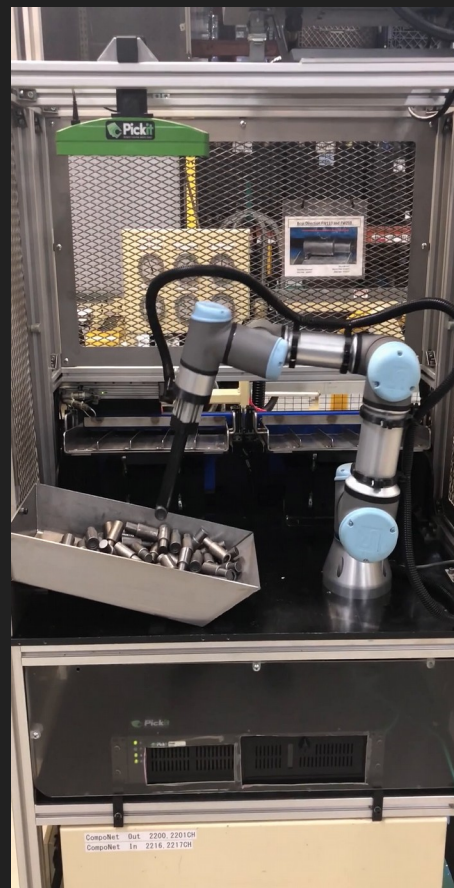


Pick-it in Action

*"The Pick-it product works great and has an **expected ROI of 2 years**, including the four Universal Robots.*

*"Getting started with **Pick-it was very easy**. Each system was installed and seeing parts in less than an hour."*

*"After setting up four robot cells with Pick-it, we now have sufficient experience to **install and integrate it with a UR in less than an hour**."*



Pick-it in Action

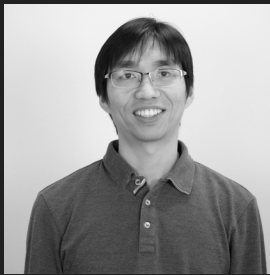
*"I quickly adopted it and learned to **program it by myself.**"*

*"Any question I had could be resolved within one or two days by the responsive Pick-it support team. Especially **the use of snapshots** made the communication with the support team very efficient.*

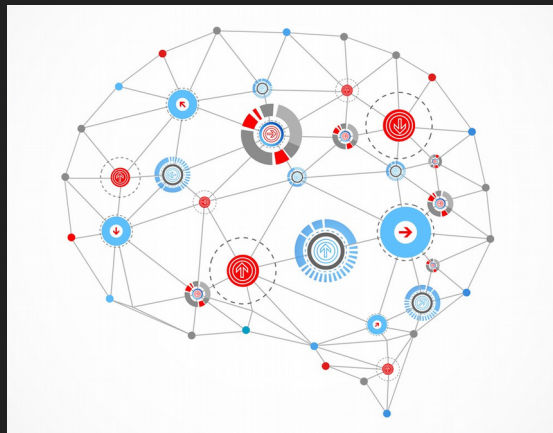
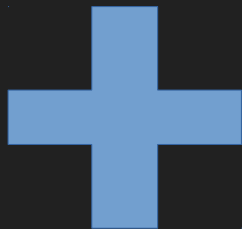
*"I already bought **four** Pick-it systems: **two of them are running in production**"*



Pick-it 2017 - 2018



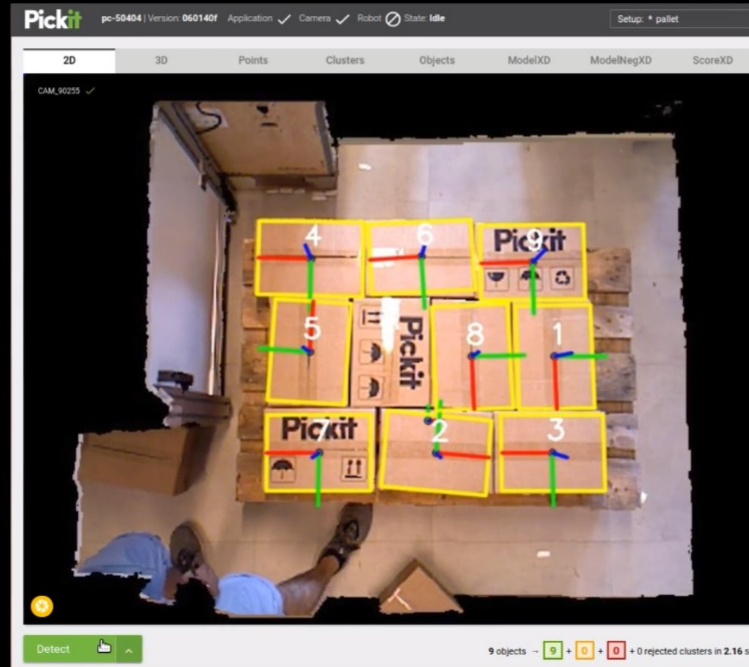
Pickit
ROBOT VISION MADE EASY



시간은 ?

가격은 ?

Pick-it 2018



1x speed

Pick-it with ABB



Pick-it at Automatica 2018



Pick-it at Automatica 2018

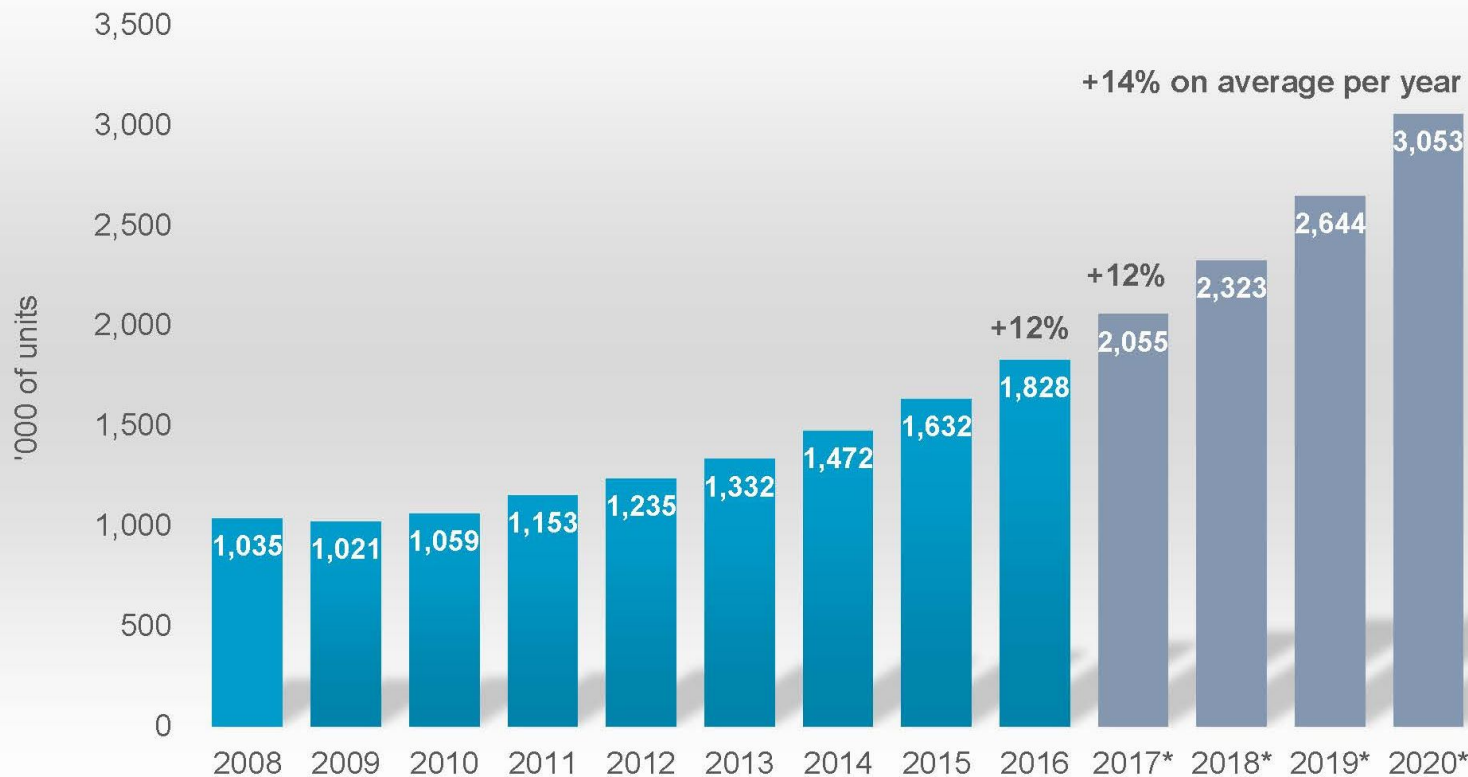
Day 1



미래는 ?



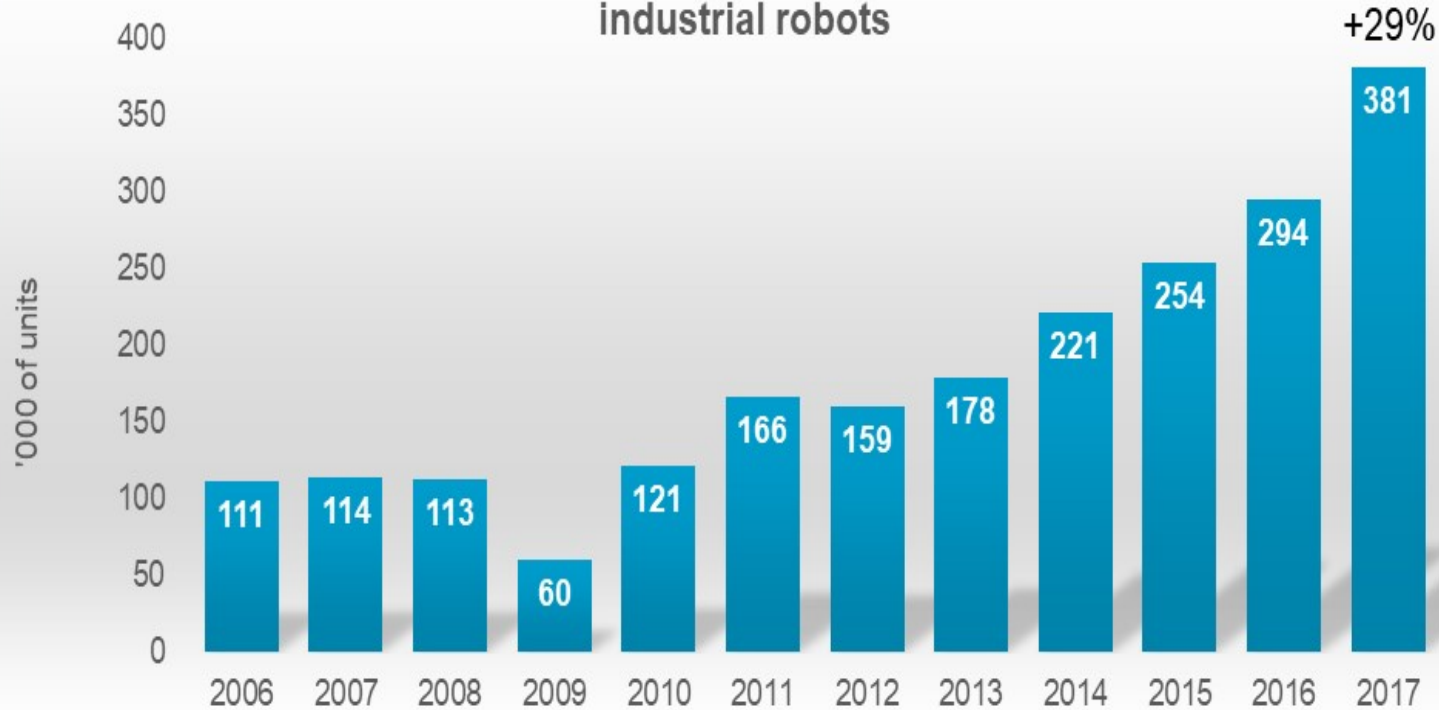
Estimated worldwide operational stock of industrial robots 2015-2016 and forecast for 2017*-2020*



*forecast

IFR World Robotics 2017

Estimated worldwide annual shipments of industrial robots



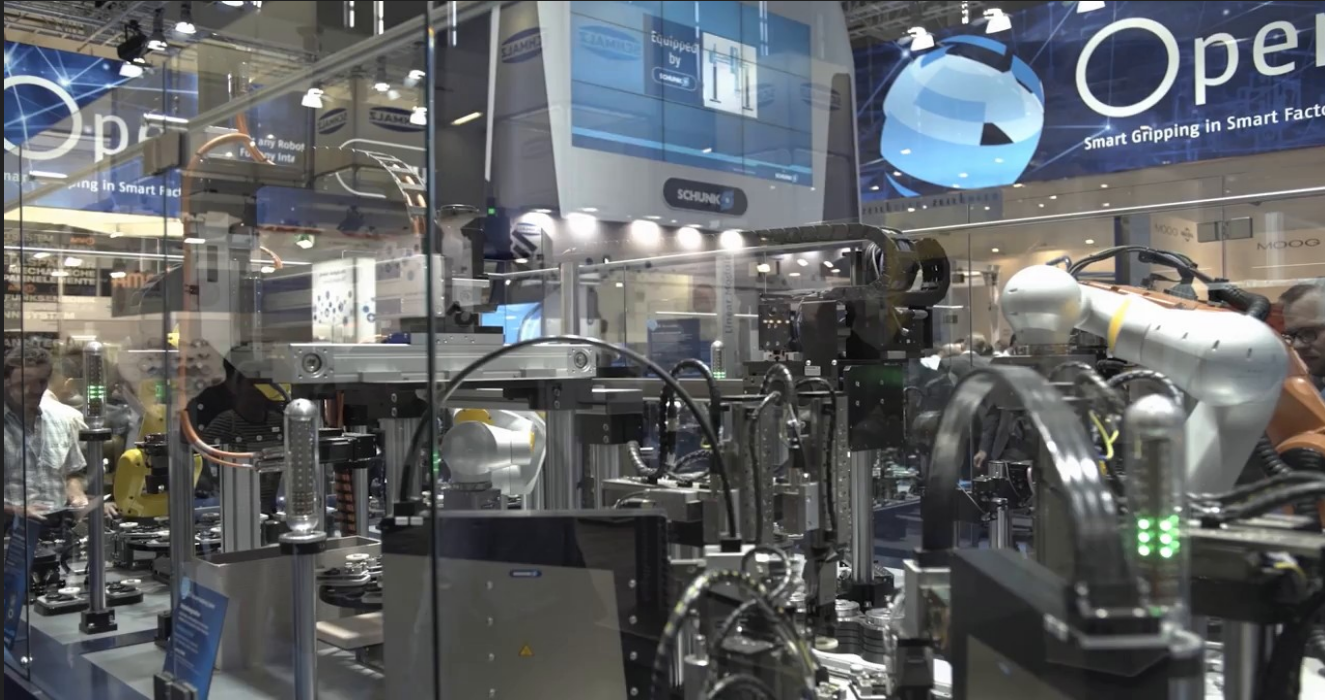
Source: IFR Statistical Department

*“Key trends such as **digitalisation, simplification and human-robot collaboration** will certainly shape the future and drive forward rapid development.”*

- IFR president Junji Tsuda -

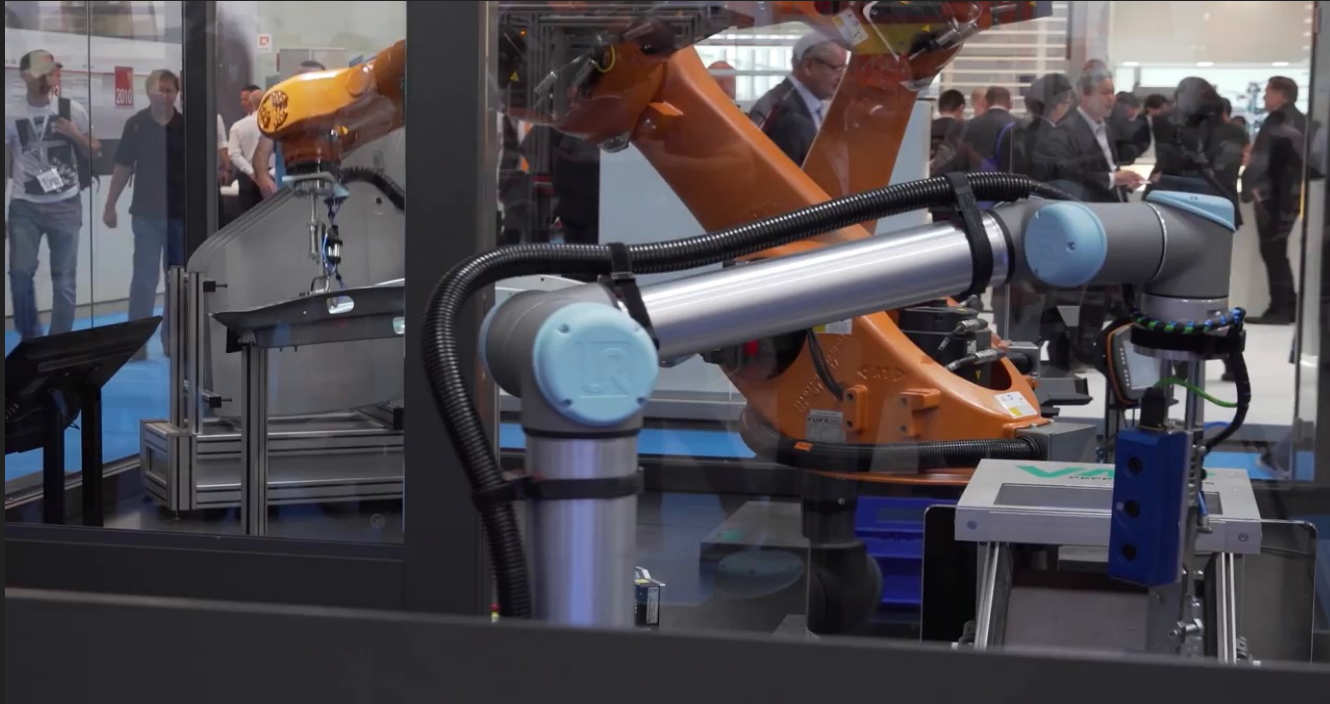
Automatica 2018 Theme

Digital transformation in Manufacturing



Automatica 2018 Theme

Digital transformation in Manufacturing



*“Key trends such as **digitalisation, simplification and human-robot collaboration** will certainly shape the future and drive forward rapid development.”*

- IFR president Junji Tsuda -

*“Key trends such as **digitalisation, simplification and human-robot collaboration with AI** certainly shaped the future and drive forward rapid development.”*

- IFR president 2020 -

감사합니다.



구성용

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www.pickit3d.com